## FIDM $\in C$

## User Manuel SQN3... SQN4...



Siemens
Servomotor
Actuator

## Use / features

The SQN3... / SQN4... actuators are designed for driving gas or air dampers of oil or gas burners of small to medium capacity, or for load-dependent control of the fuel or combustion air volume:

- In connection with P-PI or PID controllers, such as the RWF40...
- Directly via the different types of burner controls, such as LOA..., LMO..., LMG... or LFL...
- In connection with 1- or 2-wire control or 3-position controllers
- All types of actuators with:
- Impact-proof and heat-resistant plastic housing
- Screw terminals for the electrical connections
- Maintenance-free gear train, which can be disengaged
- Internal and external position indication
- Easy-to-adjust end and auxiliary switches for setting the switching points
- Holding torque: - SQN3... 0.8... 3 Nm
- SQN4... 6 Nm
- Running time: - SQN3... 4.5... 30 s
- SQN4... 120 s
- Direction of rotation: - SQN30...counterclockwise
- SQN31... / SQN41...clockwise


## Warning notes

To avoid injury to persons, damage to property or the environment, the following warning notes should be observed!
Do not interfere with or modify the actuators!

- All activities (mounting, installation and service work, etc.)
must be performed by qualified staff
- Before making any wiring changes in the connection area of the actuators, completely isolate the equipment from the mains supply (all-polar disconnection)
- Ensure protection against electric shock hazard by providing adequate protection for the connection terminals and by securing the housing cover
- Check to ensure that wiring is in an orderly state
- Fall or shock can adversely affect the safety functions. Such actuators must not be put into operation, even if they do not exhibit any damage


## Mounting notes

- Ensure that the relevant national safety regulations are complied with


## Commissioning notes

- Prior to commissioning, check to ensure that wiring is in an orderly state


## Mechanical design

- Made of impact-proof and heat-resistant plastic
- The housing accommodates:
- The reversible synchronous motor with gear train, which can be disengaged
- The camshaft of the control section
- The relays (depending on the type of actuator)
- The switches, connected to the terminals via the printed circuit board
Color: Gear train housing light-grey, cover dark-grey
- Reversible and locking-proof synchronous motor

2 - Automatic reengagement

- Pin «K»

Manual disengagement of gear train from motor by pressing pin «K1».
Adjustment of switching points

- With adjustable cams
- Scales beside the cams indicate the angle of the switching point
- Cams manually adjustable with tool supplied with the actuator Position indication
- Internally: Scale on the gear train side of the camshaft
- Externally: Scale in viewing window (refer to «Dimensions»)

Electrical connections

- Refer to «Technical data»

Gear train

- Maintenance-free

Drive shaft

- Made of black-finished steel.
- Ready fitted to the front of the gear train
- Different versions available

Mounting and fixing

- Front of the gear train is used as the mounting surface
- Actuator is secured via through-holes

Special versions for fitting potentiometer

## Fitting a potentiometer

Certain types of actuators are supplied ready prepared for fitting a potentiometer.
These actuators differ from the basic type only in that the housing is higher and that
they are prepared for accommodating a potentiometer. Accessories are not required.
The required type of potentiometer is to be ordered as a separate item (refer to «Ordering
»). In that case, the third digit after the dot in the actuator's type reference will
change from «1» to «2».
Example:
SQN31.111A2700 $\rightarrow$ basic type
SQN31.112A2700 $\rightarrow$ version for fitting a potentiometer
Conversion by the user
Users have the choice of converting a basic type of actuator to a version for fitting a potentiometer.
For that, a conversion kit type AGA32 is available (refer to «Ordering»).
Conversion of the basic type reference must be noted by the user on the actuator's
type field using a permanent felt-tip pen.

Actuators SQN30.../ counterclockwise rotation ${ }^{8}$ )

| Diagram | Drive shaft ${ }^{1}$ ) |  | Operating torque (max.) | Holding torque |  | Relay | Housing length ${ }^{1}$ ) | Types for mains voltage / mains frequency |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | 7) |  |  | AC $220 \mathrm{~V}-15 \%$ | AC $100 \mathrm{~V}-15 \%$ |
|  |  |  |  |  | pcs. | pcs. | mm | $\begin{gathered} \text { AC } 240 \mathrm{~V}+10 \% \\ 50 \ldots 60 \mathrm{~Hz}^{4)} \end{gathered}$ | $\begin{gathered} \text { AC } 110 \mathrm{~V}+10 \% \\ 50 \ldots . .60 \mathrm{~Hz}^{3)} \end{gathered}$ |
| 0 | 0 | 4.5 | 1 | 0.8 | 3 | --- | 125 | SQN30.102A2700 ${ }^{5}$ ) | --- |
| 1 | 0 | 4.5 | 1 | 0.8 | 2 | 1 | 110 | SQN30.111A2700 | SQN30.111A1700 |
| 1 | 0 | 4.5 | 1.5 | 0.8 | 2 | 1 | 110 | SQN30.111A3500 ${ }^{9}$ ) | --- |
| 2 | 0 | 4.5 | 1 | 0.8 | 1 | 2 | 110 | SQN30.121A2700 | SQN30.121A1700 |
| 2 | 0 | 4.5 | 1.5 | 0.8 | 1 | 2 | 110 | SQN30.121A3500 ${ }^{9}$ ) | --- |
| 3 | 0 | 4.5 | 1 | 0.8 | 1 | 2 | 110 | SQN30.131A2700 | SQN30.131A1700 |
| 5 | 0 | 4.5 | 1 | 0.8 | 1 | 2 | 110 | SQN30.151A2700 | SQN30.151A1700 |
| 5 | 0 | 12 | 1.8 | 1.8 | 1 | 2 | 110 | SQN30.251A2700 | SQN30.251A1700 |
| 0 | 0 | 30 | 3 | 3 | 3 | --- | 110 | SQN30.401A2700 | --- |
| 0 | 3 | 30 | 3 | 3 | 3 | --- | 110 | SQN30.401A2730 | --- |
| 0 | 0 | 30 | 3 | 3 | 3 | --- | 125 | SQN30.402A2700 ${ }^{5}$ ) | SQN30.402A1700 ${ }^{5}$ ) |
| 0 | 3 | 30 | 3 | 3 | 3 | --- | 125 | SQN30.402A2730 ${ }^{5}$ ) | --- |
| 3 | 0 | 30 | 3 | 3 | 1 | 2 | 110 | SQN30.431A2700 | --- |
| 5 | 0 | 30 | 3 | 3 | 1 | 2 | 110 | SQN30.451A2700 | --- |

Actuators SQN31... / clockwise rotation ${ }^{8}$ )

| Diagram <br> no. | Drive shaft ${ }^{1}$ ) <br> no. | $\begin{gathered} \text { Running } \\ \text { time } \\ \text { at } \left.50 \mathrm{~Hz}^{2}\right) \\ \text { for } 90^{\circ} \\ \hline \end{gathered}$ | $\begin{aligned} & \text { Operating } \\ & \text { torque } \\ & \text { (max.) } \\ & \mathrm{Nm} \\ & \hline \end{aligned}$ | Holding torque $\mathrm{Nm}$ | $\begin{gathered} \hline \mathrm{HS} \\ 7 \text { 7) } \\ \text { pcs. } \\ \hline \end{gathered}$ | Relay <br> pcs. | Housing length ${ }^{1}$ ) <br> mm | Types for mains AC 220 V -15 \% AC $240 \mathrm{~V}+10 \%$ $50 \ldots 60 \mathrm{~Hz}{ }^{4)}$ | $\begin{aligned} & \text { mains frequency } \\ & \text { AC } 100 \mathrm{~V}-15 \% \\ & \text { AC } 110 \mathrm{~V}+10 \% \\ & 50 \ldots 60 \mathrm{~Hz}{ }^{3)} \\ & \hline \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 4.5 | 1 | 0.8 | 3 | --- | 110 | SQN31.101A2700 | SQN31.101A1700 |
| 0 | 0 | 4.5 | 1 | 0.8 | 3 | --- | 125 | SQN31.102A2700 ${ }^{5}$ ) | SQN31.102A1700 ${ }^{5}$ ) |
| 1 | 0 | 4.5 | 1 | 0.8 | 2 | 1 | 110 | SQN31.111A2700 | --- |
| 1 | 6 | 4.5 | 1 | 0.8 | 2 | 1 | 110 | SQN31.111A2760 | --- |
| 2 | 0 | 4.5 | 1 | 0.8 | 1 | 2 | 110 | SQN31.121A2700 | --- |
| 2 | 3 | 4.5 | 1 | 0.8 | 1 | 2 | 110 | SQN31.121A2730 | --- |
| 2 | 6 | 4.5 | 1 | 0.8 | 1 | 2 | 110 | SQN31.121A2760 | --- |
| 5 | 0 | 4.5 | 1 | 0.8 | 1 | 2 | 110 | SQN31.151A2700 | SQN31.151A1700 |
| 5 | 3 | 4.5 | 1 | 0.8 | 1 | 2 | 110 | SQN31.151A2730 | --- |
| 2 | 0 | 12 | 1.8 | 1.8 | 1 | 2 | 110 | SQN31.221A2700 | --- |
| 2 | 3 | 12 | 1.8 | 1.8 | 1 | 2 | 110 | SQN31.221A2730 | --- |
| 5 | 0 | 12 | 1.8 | 1.8 | 1 | 2 | 110 | SQN31.251A2700 | SQN31.251A1700 |
| 5 | 3 | 12 | 1.8 | 1.8 | 1 | 2 | 110 | SQN31.251A2730 | --- |
| 5 | 0 | 12 | 1.8 | 1.8 | 1 | 2 | 125 | SQN31.252A2700 ${ }^{5}$ ) | SQN31.252A1700 ${ }^{5}$ ) |
| 5 | 0 | 15 | 2 | 1.8 | 1 | 2 | 110 | SQN31.351A2700 | --- |
| 0 | 0 | 30 | 3 | 3 | 3 | --- | 110 | SQN31.401A2700 | SQN31.401A1700 |
| 0 | 3 | 30 | 3 | 3 | 3 | --- | 110 | SQN31.401A2730 | --- |
| 0 | 6 | 30 | 3 | 3 | 3 | --- | 110 | SQN31.401A2760 | --- |
| 0 | 0 | 30 | 3 | 3 | 3 | --- | 125 | SQN31.402A2700 ${ }^{5}$ ) | SQN31.402A1700 ${ }^{5}$ ) |
| 1 | 0 | 30 | 3 | 3 | 2 | 1 | 110 | SQN31.411A2700 | --- |
| 1 | 3 | 30 | 3 | 3 | 2 | 1 | 110 | SQN31.411A2730 | --- |
| 6 | 0 | 23 | 2.5 | 2.5 | --- | 2 | 125 | SQN31.762A2700 ${ }^{5}$ ) | --- |
| 4 | 0 | 120 | 6 | 6 | 2 | 1 | 110 | SQN31.941A2700 | --- |

Actuators SQN41... $/$ clockwise rotation ${ }^{8}$ )

| Diagram | Drive | Running | Operating | Holding | HS | Relay | Housing | Types for mains voltage / mains frequency |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | shaft ${ }^{1}$ ) | time | torque | torque | 7) |  | length ${ }^{1}$ ) | AC $220 \mathrm{~V}-15 \%$ | AC $100 \mathrm{~V}-15 \%$ |
|  |  | at $50 \mathrm{~Hz}^{2}$ ) | (max.) |  |  |  |  | AC $240 \mathrm{~V}+10$ \% | AC $110 \mathrm{~V}+10$ \% |
| no. | no. | for $90^{\circ}$ | Nm | Nm | pcs. | pcs. | mm | $50 . . .60 \mathrm{~Hz}{ }^{4}$ | $50 \ldots 60 \mathrm{~Hz}{ }^{3)}$ |
| 4 | 0 | 120 | 6 | 6 | 2 | 1 | 110 | SQN41.941A2700 | --- |


| Legend | ${ }^{1}$ ) | Refer to «Dimensions» |
| :---: | :---: | :---: |
|  | $\left.{ }^{2}\right)$ | At 60 Hz , running times are about $20 \%$ shorter |
|  | $\left.{ }^{3}\right)$ | AC 100... $110 \mathrm{~V}+10 \% /-15 \%$ possible, but in case of undervoltage torque is reduced by about $20 \%$ |
|  | $\left.{ }^{4}\right)$ | AC $220 \ldots 240 \mathrm{~V}+10 \% /-15 \%$ possible, but in case of undervoltage torque is reduced by about $20 \%$ |
|  | $\left.{ }^{5}\right)$ | Suited for fitting a potentiometer (refer to «Fitting a potentiometer») |
|  | ${ }^{6}$ ) | Under nominal conditions; under extreme conditions (e.g. $+60^{\circ} \mathrm{C}, \mathrm{AC} 230 \mathrm{~V}-15 \%$ ) about -25\% |
|  | ${ }^{7}$ ) | Optional auxiliary switches (in addition to the 2 end switches) |
|  | $\left.{ }^{8}\right)$ | When facing the drive shaft and when control voltage is fed to end switch I |
|  | ${ }^{9}$ ) | On time at: $\quad-\operatorname{AC} 220 \mathrm{~V}-15 \% /+10 \%$ and $50 \mathrm{~Hz}-\max .50 \%$ |

Technical data

| General actuator data Actuator | Mains voltage | $\begin{aligned} & \text { AC } 220 \ldots . .240 \mathrm{~V}-15 \%+10 \% \\ & \text { AC } 100 \ldots 110 \mathrm{~V}-15 \%+10 \% \end{aligned}$ |
| :---: | :---: | :---: |
|  | Mains frequency | $50 . . .60 \mathrm{~Hz} \pm 6$ \% |
|  | Type of motor | synchronous motor |
|  | Power consumption | 6.5 VA |
|  | Angular position | max. $160{ }^{\circ}$ |
|  | Mounting position | optional |
|  | Degree of protection | IP 40 to DIN 40050, provided adequate cable entries and fixing screws are used |
|  | Safety class | I to VDE 0631 |
|  | Cable entry | threaded cable gland holder for $1 \times \mathrm{Pg} 9$ and $1 \times \mathrm{Pg} 11$, no locknut required |
|  |  | cable strain relief to be provided by the user (also refer to «Degree of protection»), Pg glands for all types are included in the delivery |
|  | Cable connections | screw terminals for wires having a crosssectional area of 0.5 to $2.5 \mathrm{~mm}^{2}$ |
|  | Ferrules | matching the dia. of the stranded wire |
|  | Direction of rotation | refer to «Type summary» |
|  | Torques and holding torques | refer to «Type summary» |
|  | Running times | refer to «Type summary» |
|  | Weight (on average) | approx. 800 g |
| End and auxiliary switches | Number of end switches | 2 |
|  | Number of auxiliary switches | refer to «Type summary» |
|  | Actuation | via camshaft, color-coded cams (refer to «Connection diagrams» |
|  | Switching voltage | AC 24... 250 V |
|  | Adjustment of cams in increments of | $1^{\circ}$ |
|  | Max. terminal rating at $\cos \varphi=0.9$ | under load ON, with no load OFF <br> - starting current 14 A <br> - operating current 2 A <br> under load ON...OFF <br> - starting current 7 A <br> - operating current 1 A |

