

User Manuel **SQN3... SQN4...**



Siemens Servomotor Actuator

English

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Use / features

The SQN3... / SQN4... actuators are designed for driving gas or air dampers of oil or gas burners of small to medium capacity, or for load-dependent control of the fuel or combustion air volume:

- In connection with P-PI or PID controllers, such as the RWF40...
- Directly via the different types of burner controls, such as LOA..., LMO..., LMG... or LFL...
- In connection with 1- or 2-wire control or 3-position controllers
- All types of actuators with:
- Impact-proof and heat-resistant plastic housing
- Screw terminals for the electrical connections
- Maintenance-free gear train, which can be disengaged
- Internal and external position indication
- Easy-to-adjust end and auxiliary switches for setting the switching points
- Holding torque: SQN3... 0.8...3 Nm
- SQN4... 6 Nm
- Running time: SQN3... 4.5...30 s
- SQN4... 120 s
- Direction of rotation: SQN30...counterclockwise
- SQN31... / SQN41...clockwise

Warning notes

To avoid injury to persons, damage to property or the environment, the following warning notes should be observed!

Do not interfere with or modify the actuators!

- All activities (mounting, installation and service work, etc.) must be performed by qualified staff
- Before making any wiring changes in the connection area of the actuators, completely isolate the equipment from the mains supply (all-polar disconnection)
- Ensure protection against electric shock hazard by providing adequate protection for the connection terminals and by securing the housing cover
- Check to ensure that wiring is in an orderly state
- Fall or shock can adversely affect the safety functions. Such actuators must not be put into operation, even if they do not exhibit any damage

Mounting notes

• Ensure that the relevant national safety regulations are complied with

Commissioning notes

• Prior to commissioning, check to ensure that wiring is in an orderly state

Mechanical design

- Made of impact-proof and heat-resistant plastic
- The housing accommodates:
- The reversible synchronous motor with gear train, which can be disengaged
- The camshaft of the control section
- The relays (depending on the type of actuator)
- The switches, connected to the terminals via the printed circuit board

Color: Gear train housing light-grey, cover dark-grey

- Reversible and locking-proof synchronous motor
- Automatic reengagement

- Pin «K

Manual disengagement of gear train from motor by pressing pin $\kappa K1$ ».

Adjustment of switching points

- With adjustable cams
- Scales beside the cams indicate the angle of the switching point
- Cams manually adjustable with tool supplied with the actuator Position indication
- Internally: Scale on the gear train side of the camshaft
- Externally: Scale in viewing window (refer to «Dimensions») Electrical connections
- Refer to «Technical data»

Gear train

- Maintenance-free

Drive shaft

- Made of black-finished steel.
- Ready fitted to the front of the gear train
- Different versions available

Mounting and fixing

- Front of the gear train is used as the mounting surface
- Actuator is secured via through-holes

Special versions for fitting potentiometer

Fitting a potentiometer

Certain types of actuators are supplied ready prepared for fitting a potentiometer.

These actuators differ from the basic type only in that the housing is higher and that

they are prepared for accommodating a potentiometer. Accessories are not required.

The required type of potentiometer is to be ordered as a separate item (refer to «Ordering

»). In that case, the third digit after the dot in the actuator's type reference will

change from «1» to «2».

Example:

 $SQN31.111A2700 \rightarrow basic type$

SQN31.112A2700 → version for fitting a potentiometer

Conversion by the user

Users have the choice of converting a basic type of actuator to a version for fitting a potentiometer.

For that, a conversion kit type AGA32 is available (refer to «Ordering»).

Conversion of the basic type reference must be noted by the user on the actuator's

type field using a permanent felt-tip pen.



Diagram	Drive	Running	Operating	Holding	HS	Relay	Housing	Types for mains voltage / mains frequency	
	shaft 1)	time	torque	torque	7)		length 1)	AC 220 V -15 %	AC 100 V -15 %
		at 50 Hz 2)	(max.)					AC 240 V +10 %	AC 110 V +10 %
no.	no.	for 90°	Nm	Nm	pcs.	pcs.	mm	5060 Hz ⁴⁾	5060 Hz ³⁾
0	0	4.5	1	0.8	3		125	SQN30.102A2700 ⁵)	
1	0	4.5	1	8.0	2	1	110	SQN30.111A2700	SQN30.111A1700
1	0	4.5	1.5	0.8	2	1	110	SQN30.111A3500 ⁹)	
2	0	4.5	1	8.0	1	2	110	SQN30.121A2700	SQN30.121A1700
2	0	4.5	1.5	0.8	1	2	110	SQN30.121A3500 ⁹)	
3	0	4.5	1	0.8	1	2	110	SQN30.131A2700	SQN30.131A1700
5	0	4.5	1	8.0	1	2	110	SQN30.151A2700	SQN30.151A1700
5	0	12	1.8	1.8	1	2	110	SQN30.251A2700	SQN30.251A1700
0	0	30	3	3	3		110	SQN30.401A2700	
0	3	30	3	3	3		110	SQN30.401A2730	
0	0	30	3	3	3		125	SQN30.402A2700 ⁵)	SQN30.402A1700 ⁵)
0	3	30	3	3	3		125	SQN30.402A2730 ⁵)	
3	0	30	3	3	1	2	110	SQN30.431A2700	
5	0	30	3	3	1	2	110	SQN30.451A2700	

Actuators SQN31... / clockwise rotation 8)

Actuators ognor / clockwise rotation									
Diagram	Drive	Running	Operating	Holding	HS	Relay	Housing	Types for mains voltage / mains frequency	
	shaft 1)	time	torque	torque	7)		length 1)	AC 220 V -15 %	AC 100 V -15 %
		at 50 Hz ²)	(max.)					AC 240 V +10 %	AC 110 V +10 %
no.	no.	for 90°	Nm	Nm	pcs.	pcs.	mm	5060 Hz ⁴⁾	5060 Hz ³⁾
0	0	4.5	1	8.0	3		110	SQN31.101A2700	SQN31.101A1700
0	0	4.5	1	0.8	3		125	SQN31.102A2700 ⁵)	SQN31.102A1700 ⁵)
1	0	4.5	1	0.8	2	1	110	SQN31.111A2700	
1	6	4.5	1	0.8	2	1	110	SQN31.111A2760	
2	0	4.5	1	0.8	1	2	110	SQN31.121A2700	
2	3	4.5	1	0.8	1	2	110	SQN31.121A2730	
2	6	4.5	1	0.8	1	2	110	SQN31.121A2760	
5	0	4.5	1	0.8	1	2	110	SQN31.151A2700	SQN31.151A1700
5	3	4.5	1	0.8	1	2	110	SQN31.151A2730	
2	0	12	1.8	1.8	1	2	110	SQN31.221A2700	
2	3	12	1.8	1.8	1	2	110	SQN31.221A2730	
5	0	12	1.8	1.8	1	2	110	SQN31.251A2700	SQN31.251A1700
5	3	12	1.8	1.8	1	2	110	SQN31.251A2730	
5	0	12	1.8	1.8	1	2	125	SQN31.252A2700 ⁵)	SQN31.252A1700 ⁵)
5	0	15	2	1.8	1	2	110	SQN31.351A2700	
0	0	30	3	3	3		110	SQN31.401A2700	SQN31.401A1700
0	3	30	3	3	3		110	SQN31.401A2730	
0	6	30	3	3	3		110	SQN31.401A2760	
0	0	30	3	3	3		125	SQN31.402A2700 ⁵)	SQN31.402A1700 ⁵)
1	0	30	3	3	2	1	110	SQN31.411A2700	
1	3	30	3	3	2	1	110	SQN31.411A2730	
6	0	23	2.5	2.5		2	125	SQN31.762A2700 ⁵)	
4	0	120	6	6	2	1	110	SQN31.941A2700	

Actuators SQN41... / clockwise rotation 8)

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Diagram	Drive	Running	Operating	Holding	HS	Relay	Housing	Types for mains voltage	ge / mains frequency
	shaft 1)	time	torque	torque	7)		length 1)	AC 220 V -15 %	AC 100 V -15 %
		at 50 Hz ²)	(max.)					AC 240 V +10 %	AC 110 V +10 %
no.	no.	for 90°	Nm	Nm	pcs.	pcs.	mm	5060 Hz ⁴⁾	5060 Hz ³⁾
4	0	120	6	6	2	1	110	SQN41.941A2700	

Legend

- 1) Refer to «Dimensions»
- $^{2}\dot{)}~$ At 60 Hz, running times are about 20 % shorter
- $^{4}\dot{)}~$ AC 220...240 V +10 % / -15 % possible, but in case of undervoltage torque is reduced by about 20 %
- $^{5)}$ Suited for fitting a potentiometer (refer to «Fitting a potentiometer»)
- 6) Under nominal conditions; under extreme conditions (e.g. +60 °C, AC 230 V –15 %) about –25 %
- 7) Optional auxiliary switches (in addition to the 2 end switches)
- ⁹) On time at:
- AC 220 V -15 % / +10 % and 50 Hz max. 50 %



Technical data

General	actuator	data
Actuato	r	

Maine veltage	AC 220240 V –15 % +10 %					
Mains voltage	AC 220240 V = 15 % + 10 % AC 100110 V = 15 % + 10 %					
Mains fraguency	5060 Hz ±6 %					
Mains frequency Type of motor	synchronous motor					
Power consumption	6.5 VA					
Angular position	max. 160°					
Mounting position	optional					
Degree of protection	IP 40 to DIN 40050, provided adequate					
Octoberation	cable entries and fixing screws are used					
Safety class	I to VDE 0631					
Cable entry	threaded cable gland holder for					
	1 x Pg9 and 1 x Pg11, no locknut required					
	cable strain relief to be provided by the user					
	(also refer to «Degree of protection»),					
	Pg glands for all types are included in the					
	delivery					
Cable connections	screw terminals for wires having a cross-					
	sectional area of 0.5 to 2.5 mm²					
Ferrules	matching the dia. of the stranded wire					
Direction of rotation	refer to «Type summary»					
Torques and holding torques	refer to «Type summary»					
Running times	refer to «Type summary»					
Weight (on average)	approx. 800 g					
Number of end switches	2					
Number of auxiliary switches	refer to «Type summary»					
Actuation	via camshaft, color-coded cams (refer to					
	«Connection diagrams»					
Switching voltage	AC 24250 V					
Adjustment of cams in increments of	1°					
Max. terminal rating at	under load ON, with no load OFF					
$\cos \varphi = 0.9$	- starting current 14 A					
•	- operating current 2 A					
	under load ONOFF					
	- starting current 7 A					
	- operating current 1 A					
	. J					

End and auxiliary switches